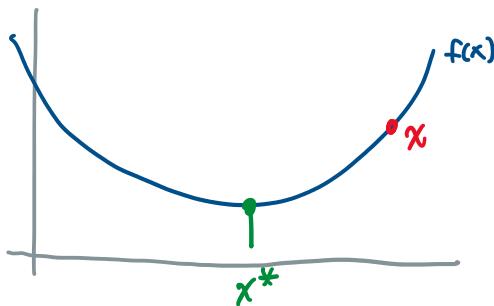


# Gradient Descent

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Let's look at 1-D case:  $f(x)$



- if  $x > x^*$   $\Leftrightarrow f'(x) > 0$
- if  $x < x^*$   $\Leftrightarrow f'(x) < 0$
- if  $x = x^*$   $\Leftrightarrow f'(x) = 0$

Algorithm:

- ① Initialize  $x$  to some value
- ② If  $f'(x)$  is close to 0, then done ✓  
else if  $f'(x) > 0$ , then  $x_{i+1} = x_i - \eta$  step size  
else if  $f'(x) < 0$ , then  $x_{i+1} = x_i + \eta$  step size

If step size too small: algorithm too slow  
too large: oscillation, no convergence.  
typically: step size  $\downarrow$  over iterations.

for  $d > 1$ :

$$\begin{aligned} f(\underline{x}_1) &= f(\underline{x}_0 + \eta \cdot \underline{v}) \\ &= f(\underline{x}_0) + \eta \underline{v}^T \nabla f(\underline{x}_0) + \dots \end{aligned}$$

Some direction to minimize  $f(\underline{x})$

ignore

$$\begin{aligned} &\approx f(\underline{x}_0) + \eta \underline{v}^T \nabla f(\underline{x}_0) \\ \Rightarrow \underline{v}^* &= \underset{\|\underline{v}\|=1}{\operatorname{argmin}} f(\underline{x}_0) + \eta \underline{v}^T \nabla f(\underline{x}_0) \end{aligned}$$

learning rate

not minimizable

minimize this

$$\underline{v}^* = -\frac{\nabla f(\underline{x}_0)}{\|\nabla f(\underline{x}_0)\|}$$

Updating Weights:

adaptive "learning rate"

Req. 1:

$$w(t+1) = w(t) + \eta_t \cdot v_t$$

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$$\underline{w}(t+1) = \underline{w}(t) + \eta_t \cdot \underline{v}_t$$
$$\eta_t = \eta \cdot \frac{\|\nabla E_{in}\|}{\|\nabla f(x_t)\|}$$
$$\eta_t \cdot \underline{v}_t = -\eta \nabla f(x_t)$$

Req 2: Initialization of weights

Recall in perceptron we initialize to  $\phi$

⚠ To avoid symmetry, we initialise weights to random values (gaussian)

$$\underline{w}(t=0) = \text{normal}(0, I)$$

Req. 3: Termination

▷ could be # of iterations

▷ could be length of gradient :  $\|\nabla E_{in}\| < \delta_1$ ,  
error :  $E_{in} < \delta_2$

— change of error :  $|\Delta E_{in}| < \delta_3$

Summary:

① Initialize weights at  $t=0$  w/  $\underline{w}(t=0)$

② for  $t=1, 2, \dots$

③ Compute  $\nabla E_{in}(\underline{w}(t))$

④ Set direction  $\underline{v}$  to  $-\frac{\nabla E}{\|\nabla E\|}$

⑤ Update weights

$$\underline{w}(t+1) = \underline{w}(t) + \eta \cdot \underline{v}_t$$

⑥ Iterate until weights are satisfactory.

## Gradient Descent in Logistic Regression

Recall logistic regression cost function:

$$E_{in} = \frac{1}{N} \cdot \sum_{n=1}^N \underbrace{\log(1 + e^{-y_n \cdot \underline{w}^T \underline{x}_n})}_{e_n}$$

$$\begin{aligned}\nabla E_{in} &= \frac{\partial E_{in}}{\partial \underline{w}} = \frac{1}{N} \sum_{n=1}^N \left( \frac{\partial E_{in}}{\partial w_i} \right) \\ &= \frac{1}{N} \sum_{n=1}^N \frac{1}{\log(1 + e^{-y_n \underline{w}^T \underline{x}_n})} \cdot \left( e^{-y_n \underline{w}^T \underline{x}_n} \right) (-y_n \underline{x}_n) \\ &= \frac{1}{N} \sum_{n=1}^N \frac{\partial u \underline{x}_n}{1 + e^{-y_n \underline{w}^T \underline{x}_n}}\end{aligned}$$

Ex. linear regression solve vs. GD.

$$f(\underline{x}) \equiv E_{in}(\underline{w}) = \frac{1}{N} \sum_{n=1}^N (\underline{w}^T \underline{x}_n - y_n)^2$$

Recall closed form sol:  $\underline{X}^T \underline{X} \underline{w}^* = \underline{X}^T \underline{y}$

$$\underline{w}^* = \underline{X}^T \underline{y} (\underline{X}^T \underline{X})^{-1}$$

computation complexity:  $\mathcal{O}(N \cdot d^2 + d^3)$  operations

Alternatively we could use gradient descent.

$$\underline{w}(t+1) = \underline{w}(t) - \eta \cdot \frac{2}{N} \sum_{n=1}^N (\underline{w}^T(t) \underline{x}_n - y_n) \cdot \underline{x}_n$$

$$\underline{w}(t+1) = \underline{w}(t) - \eta \cdot \frac{2}{N} \sum_{n=1}^N (\underline{w}^T(t) \underline{x}_n - y_n) \cdot \underline{x}_n$$

Complexity:  $O(N \times d \times \frac{I}{\eta})$  operations  
iterations

$\Rightarrow$  gradient descent is faster if d is large  
 $\Rightarrow$  gradient descent is not good for large N  
 (gradient is expensive for large N)